



# NAVI: Neuro-Adaptive Vehicle Interface

Johann Chen, Madeleine Korver, Nathan Phillips | Mentors: Jundi Liu Ph.D., Thomas Lenz

## Problem Statement

Can **situational awareness** and **workload** of a remote operator be improved by:

- **Specializing** operators' tasks and locations
- Altering the duration and variability of the **time between tasks**

## Background



**Robotaxis** - Autonomous vehicles without a driver present. These vehicles often encounter **edge cases** where they fail



**Remote Operators** - Humans who provide high-level assistance to robotaxis if they encounter edge cases

### Problems With Remote Operators



#### Situation Awareness

- Remote operators are in a remote environment
- Limited time analyzing the robotaxi
- Lack of visual input



#### Workload

- Too high or too low taskload
  - Passive/Active fatigue
- Complex scenarios
- Time pressure

### Remote Operator Queue



#### Queuing

- Each edge case must be distributed to a **fleet of operators**
- As robotaxi numbers increase, **continuous monitoring** of multiple vehicles will be **infeasible**
- **Queuing systems** will allow fleet and operators to scale arbitrarily
  - Servers: remote assistants
  - Jobs: robotaxi assistance requests

#### Algorithm

- How should jobs and servers be **matched**?
  - **Evenly distribute load** by assigning jobs to longest inactive server
  - **Appropriately load** operators through proper staffing levels
  - **Exploit local knowledge** by assigning jobs to operators who know that area
  - **Develop expertise** by allowing operators to specialize in types of task
- Queues well studied, and humans well studied, but **no studies about how queues affect humans**

### Potential Improvements & Hypotheses

- Speed up the gain of **situational awareness** and **task performance**
- Manage **workload** to avoid passive or active fatigue
- Improve **safety** through better decisions

## Methods

### Testing

- Test was given through our experimental GUI made using **Carla** and **Pygame**
- Test was prepared with tasks consisting of **different durations** between tasks, **variability**, **task types**, and **location**
- **Situational awareness** and **workload** was determined by metrics, such as **surveys**, **physiological data**, and **simulator statistics**

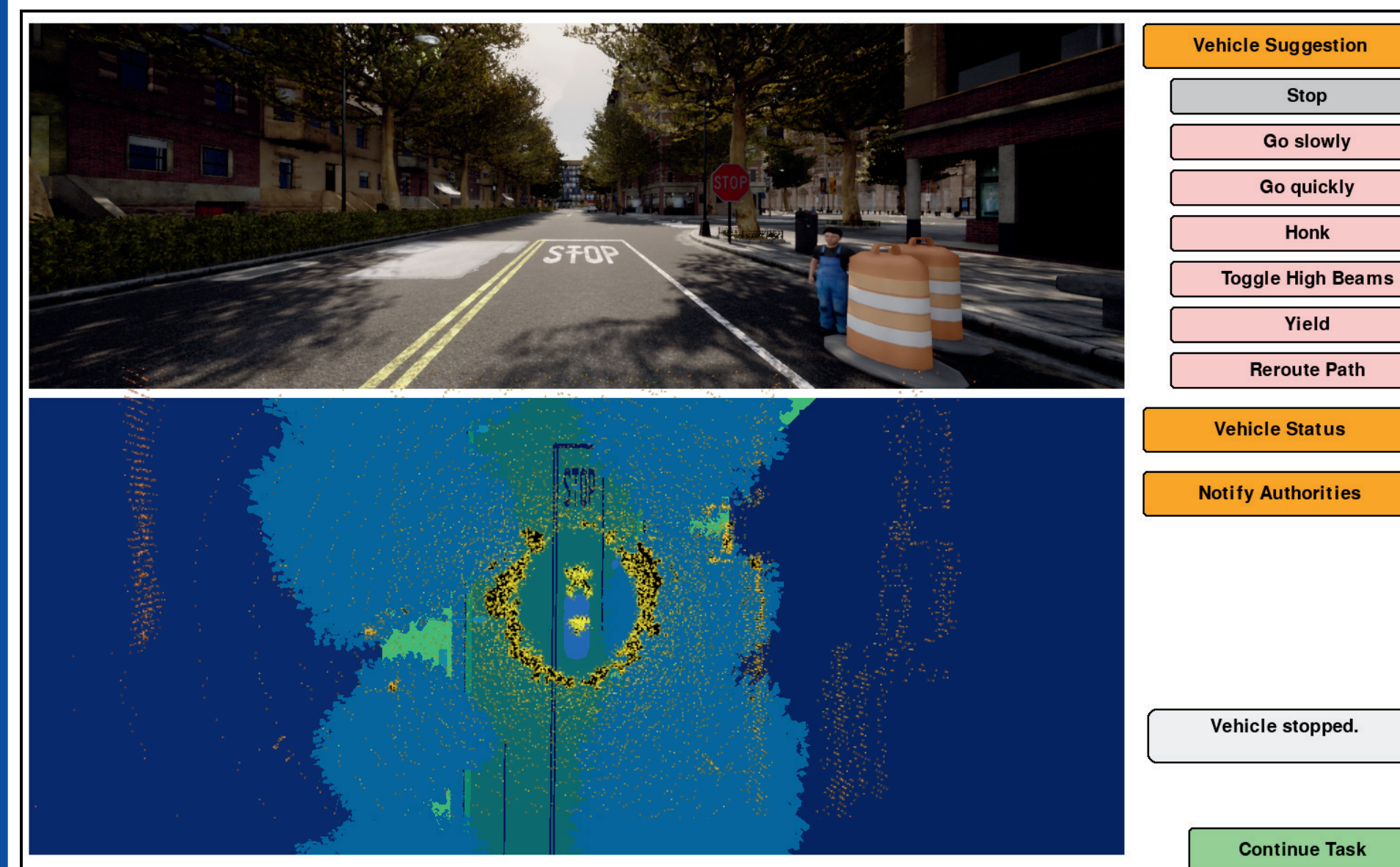


Figure 1: Experimental GUI utilizing Pygame and CARLA

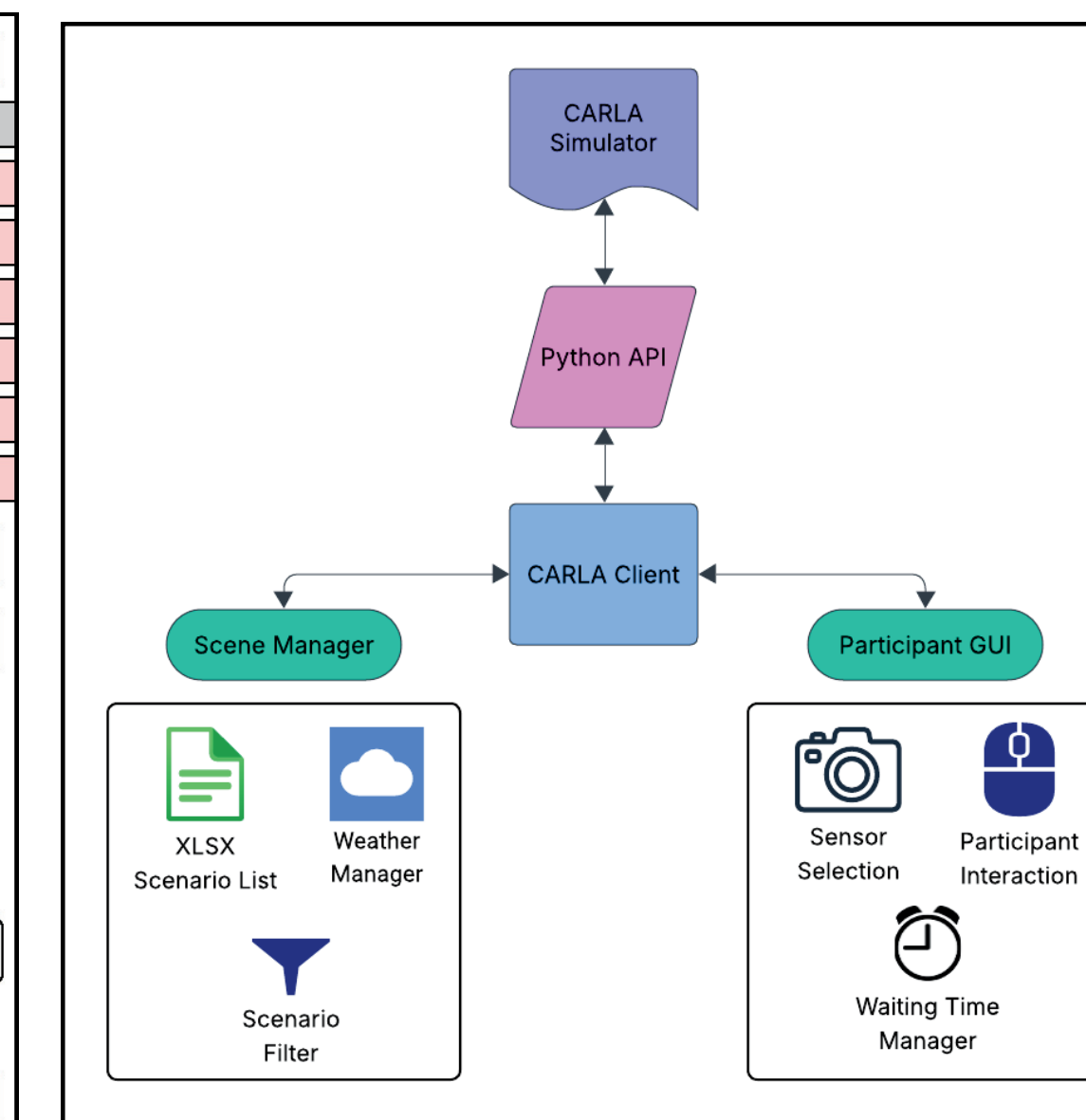
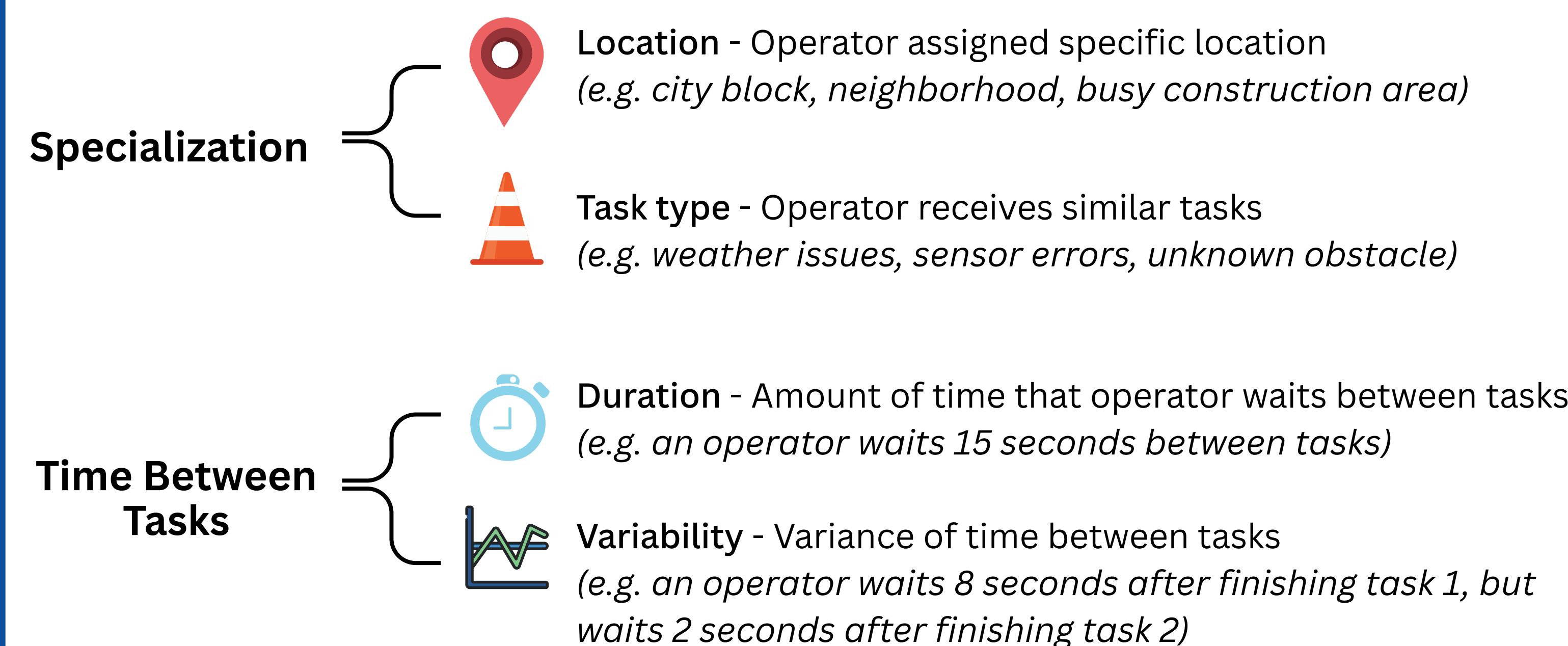
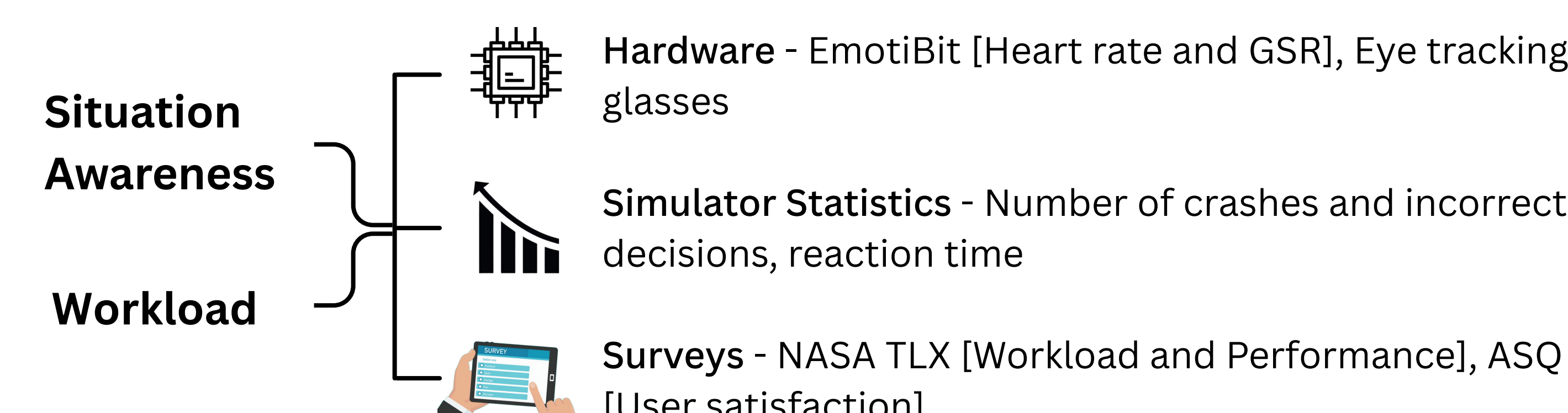


Figure 2: CARLA Remote Assistance Flowchart

### Independent Variables



### Dependent Variables



## Pilot Testing

### Goal

- **Assess** the current Remote Operator Simulator (GUI & tasks)
- Analyze **preliminary data**



Figure 3: Pilot testing with participants

### Takeaways

- Insight into human subjects testing
  - Importance of **qualitative feedback**
  - Ideas for improvement: **tasks**, **interface**
  - Importance of **note-taking**
- Subjects reported a strong learning effect: **training period** needed
- **More testing needed** for clear results

### Pilot Data

- **Two** subjects
- More testing planned for **Fall 2025**

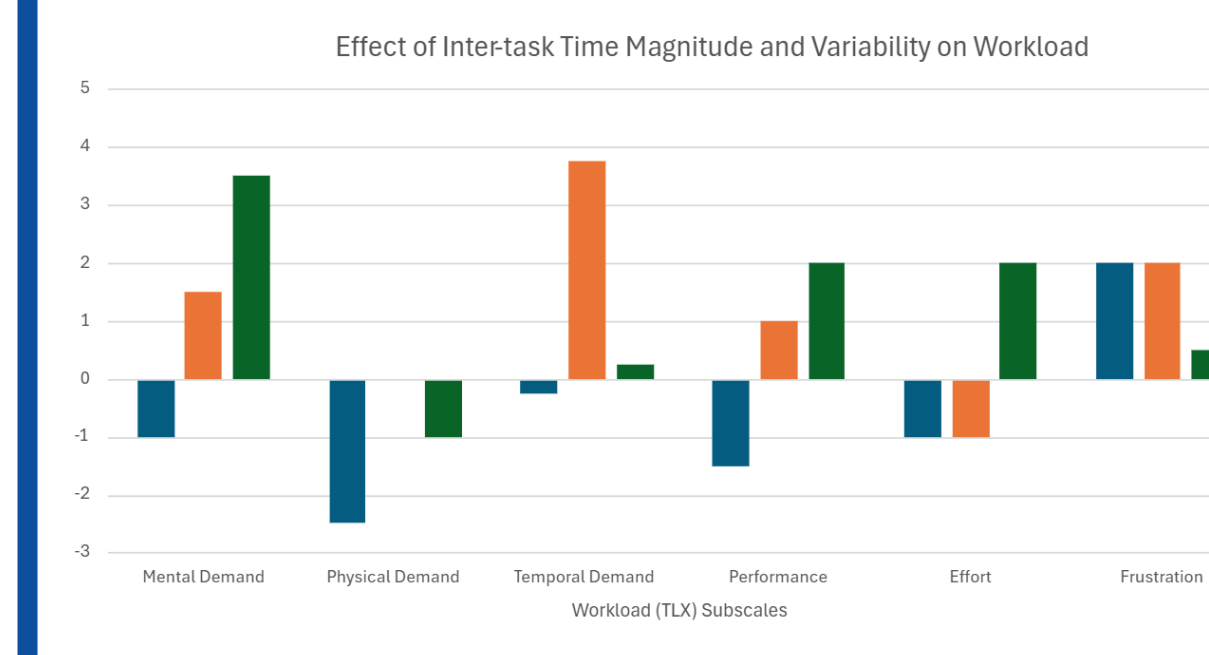


Figure 4: Pilot testing participant workload

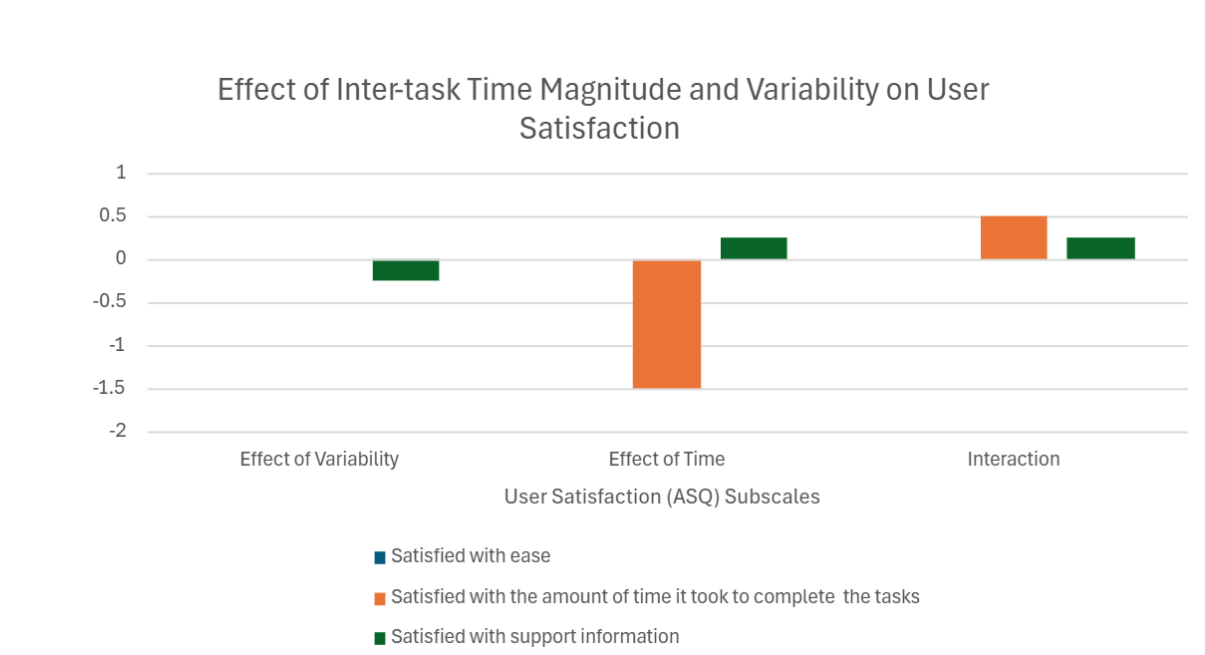


Figure 5: Pilot testing participant satisfaction

### Discussion

- The **way tasks are presented** affects user perception of **performance**, **workload**
  - **Queueing** strategies can affect **performance**
- **Variability** decreased **mental demand**, **performance**, and **physical demand**
- Longer **waiting time** increased **mental demand** and **perception of performance**
- Users were **dissatisfied** when waiting time was **longer**.

## Future Work

- **More testing**
- Validation of **generalizability and relevance** of tasks to industry
- Analysis of eye tracking and biometric data for **objective workload metrics**
- Road map for **industry takeaways**

